

Statistical modelling under epistemic data imprecision

Some results, next steps, questions, . . .

Julia Plass, Thomas Augustin
Georg Schollmeyer, Marco Cattaneo

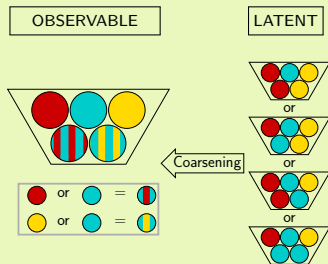
Department of Statistics, Ludwigs-Maximilians University



WPMSIIP 2015, 2nd of September 2015

Epistemic imprecision:

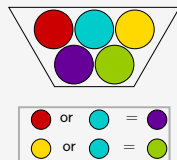
"Imprecise observation of something precise"



⇒ Truth is hidden due to the underlying coarsening mechanism

Ontic imprecision:

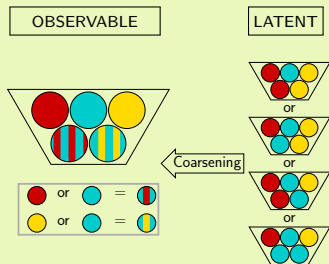
"Precise observation of something imprecise"



⇒ Truth is represented by coarse observation

Epistemic imprecision:

"Imprecise observation of something precise"



⇒ Truth is hidden due to the underlying coarsening mechanism

Examples:

- Matched data sets with partially overlapping variables
- Coarsening as anonymization technique
- Missing data as special case

Here: PASS-data

\mathcal{Y} : income, \mathcal{X} : UBI

$\Omega_{\mathcal{Y}} = \{<, \geq, na\}$

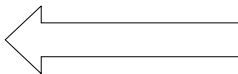
$\Omega_{\mathcal{X}} = \{0 \text{ (no)}, 1 \text{ (yes)}\}$

Basic problem

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{y}_i), \quad i = 1, \dots, n$$



coarsening mechanism

$$q_{\mathcal{Y}_i|y_i} = P(\mathcal{Y}_i = \mathcal{y}_i | Y_i = y_i)$$

LATENT

Y latent variable

Main goal:

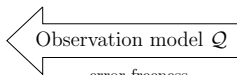
Estimation of

$$\pi_{ij} = P(Y_i = j)$$

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{y}_i), i = 1, \dots, n$$



coarsening mechanism

$$q_{\mathcal{Y}_i|y_i} = P(\mathcal{Y}_i = \mathcal{y}_i | Y_i = y_i)$$

LATENT

Y latent variable

Main goal:

Estimation of

$$\pi_{ij} = P(Y_i = j)$$

1. Frequentist approach:

Find maximum-likelihood estimator of

$$\boldsymbol{\gamma} = (\mathbf{q}_{\mathcal{Y}_i|y_i}^T, \boldsymbol{\pi}_y^T)^T$$

(i.i.d. case , regression case)

2. Bayesian approach:

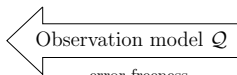
Find posterior mean

(Next step)

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{y}_i), i = 1, \dots, n$$



coarsening mechanism

$$q_{\mathcal{Y}_i|y_i} = P(\mathcal{Y}_i = \mathcal{y}_i | Y_i = y_i)$$

LATENT

Y latent variable

Main goal:

Estimation of

$$\pi_{ij} = P(Y_i = j)$$

1. Frequentist approach:

Find maximum-likelihood estimator of

$$\gamma = (\mathbf{q}_{\mathcal{Y}_i|y_i}^T, \boldsymbol{\pi}_y^T)^T$$

(i.i.d. case , regression case)

2. Bayesian approach:

Find posterior mean

(Next step)

Basic idea for the i.i.d. case

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}i} = P(\mathcal{Y}_i = \mathcal{Y}i), \quad i = 1, \dots, n$$

Use random-set perspective and determine maximum-likelihood estimator $\hat{p}_{\mathcal{Y}}$

Likelihood for parameters $\mathbf{p} = (p_1, \dots, p_{|\Omega_{\mathcal{Y}}|-1})^T$

$L(\mathbf{p}) \propto \prod_{\mathcal{Y} \in \Omega_{\mathcal{Y}}} p_{\mathcal{Y}}^{n_{\mathcal{Y}}}$ is uniquely maximized by

$$\hat{p}_{\mathcal{Y}} = \frac{n_{\mathcal{Y}}}{n}, \quad \mathcal{Y} \in \{1, \dots, |\Omega_{\mathcal{Y}}| - 1\}$$

and thus $\hat{p}_{|\Omega_{\mathcal{Y}}|} = 1 - \sum_{m=1}^{|\Omega_{\mathcal{Y}}|-1} \hat{p}_m$.

Observation model \mathcal{Q}
error-freeness

coarsening mechanism
 $q_{\mathcal{Y}|y} = P(\mathcal{Y} = \mathcal{Y} | Y = y)$

Use the connection
between \mathbf{p} and $\boldsymbol{\gamma}$

$$\Phi(\boldsymbol{\gamma}) = \mathbf{p}$$

and the invariance of the likelihood under parameter transformations, i.e.:

$$\hat{\Gamma} = \{\boldsymbol{\gamma} \mid \Phi(\boldsymbol{\gamma}) = \hat{\mathbf{p}}\}$$

LATENT

Y latent variable

Main goal:

Estimation of $\pi_{ij} = P(Y_i = j)$
 $\pi_{i1} = \pi_1, \dots, \pi_{iK} = \pi_K$

$$\boldsymbol{\gamma} = (\mathbf{q}_{\mathcal{Y}|y}^T, \boldsymbol{\pi}_y^T)^T$$

$$\hat{\pi}_y \in \left[\frac{n_{(y)}}{n}, \frac{\sum_{\mathcal{Y} \geq y} n_{\mathcal{Y}}}{n} \right]$$
$$\hat{q}_{\mathcal{Y}|y} \in \left[0, \frac{n_{\mathcal{Y}}}{n_{(y)} + n_{\mathcal{Y}}} \right]$$

Basic idea for the i.i.d. case

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{Y}_i), \quad i = 1, \dots, n$$

Use random-set perspective and determine maximum-likelihood estimator $\hat{p}_{\mathcal{Y}}$

Likelihood for parameters $\mathbf{p} = (p_1, \dots, p_{|\Omega_{\mathcal{Y}}|-1})^T$
 $L(\mathbf{p}) \propto \prod_{\mathcal{Y} \in \Omega_{\mathcal{Y}}} p_{\mathcal{Y}}^{n_{\mathcal{Y}}}$ is uniquely maximized by

$$\hat{p}_{\mathcal{Y}} = \frac{n_{\mathcal{Y}}}{n}, \quad \mathcal{Y} \in \{1, \dots, |\Omega_{\mathcal{Y}}| - 1\}$$

and thus $\hat{p}_{|\Omega_{\mathcal{Y}}|} = 1 - \sum_{m=1}^{|\Omega_{\mathcal{Y}}|-1} \hat{p}_m$.

← Observation model \mathcal{Q}
error-freeness

coarsening mechanism

$$q_{\mathcal{Y}|y} = P(\mathcal{Y} = \mathcal{Y} | Y = y)$$

Use the **connection**
between \mathbf{p} and $\boldsymbol{\gamma}$

$$\Phi(\boldsymbol{\gamma}) = \mathbf{p}$$

and the **invariance of the likelihood**
under parameter transformations, i.e.:

$$\hat{\Gamma} = \{\boldsymbol{\gamma} \mid \Phi(\boldsymbol{\gamma}) = \hat{\mathbf{p}}\}$$

LATENT

Y latent variable

Main goal:

Estimation of $\pi_{ij} = P(Y_i = j)$
 $\pi_{i1} = \pi_1, \dots, \pi_{iK} = \pi_K$

$$\boldsymbol{\gamma} = (\mathbf{q}_{\mathcal{Y}|y}^T, \boldsymbol{\pi}_y^T)^T$$

$$\hat{\pi}_y \in \left[\frac{n_{(y)}}{n}, \frac{\sum_{\mathcal{Y} \ni y} n_{\mathcal{Y}}}{n} \right]$$
$$\hat{q}_{\mathcal{Y}|y} \in \left[0, \frac{n_{\mathcal{Y}}}{n_{(y)} + n_{\mathcal{Y}}} \right]$$

Basic idea for the i.i.d. case

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{Y}_i), \quad i = 1, \dots, n$$

LATENT

\mathcal{Y} latent variable

Main goal:

$$\text{Estimation of } \pi_{ij} = P(Y_i = j) \\ \pi_{i1} = \pi_1, \dots, \pi_{iK} = \pi_K$$

Observation model \mathcal{Q}
error-freeness

$$\text{coarsening mechanism} \\ q_{\mathcal{Y}|y} = P(\mathcal{Y} = \mathcal{Y} | Y = y)$$

$$\gamma = (q_{\mathcal{Y}|y}^T, \pi_y^T)^T$$

Use random-set perspective and determine maximum-likelihood estimator $\hat{p}_{\mathcal{Y}}$

Likelihood for parameters $\mathbf{p} = (p_1, \dots, p_{|\Omega_{\mathcal{Y}}|-1})^T$

$L(\mathbf{p}) \propto \prod_{\mathcal{Y} \in \Omega_{\mathcal{Y}}} p_{\mathcal{Y}}^{n_{\mathcal{Y}}}$ is *uniquely* maximized by

$$\hat{p}_{\mathcal{Y}} = \frac{n_{\mathcal{Y}}}{n}, \quad \mathcal{Y} \in \{1, \dots, |\Omega_{\mathcal{Y}}|-1\}$$

and thus $\hat{p}_{|\Omega_{\mathcal{Y}}|} = 1 - \sum_{m=1}^{|\Omega_{\mathcal{Y}}|-1} \hat{p}_m$.

Use the **connection**
between \mathbf{p} and γ
 $\Phi(\gamma) = \mathbf{p}$

and the **invariance of the likelihood**
under parameter transformations, i.e.:

$$\hat{\Gamma} = \{\gamma \mid \Phi(\gamma) = \hat{\mathbf{p}}\}$$

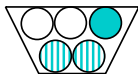
$$\hat{\pi}_y \in \left[\frac{n_{(y)}}{n}, \frac{\sum_{\mathcal{Y} \supseteq y} n_{\mathcal{Y}}}{n} \right]$$

$$\hat{q}_{\mathcal{Y}|y} \in \left[0, \frac{n_{\mathcal{Y}}}{n_{(y)} + n_{\mathcal{Y}}} \right]$$

Basic idea for the i.i.d. case

OBSERVATION

\mathcal{Y} coarse data

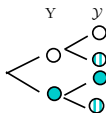


Observation model \mathcal{Q}

error-freeness

LATENT

Y latent variable



$\Phi(\cdot)$ is not injective:

$$\left(\hat{p}_{\circlearrowleft}^{(MLE)} = \frac{2}{5}, \hat{p}_{\bullet}^{(MLE)} = \frac{1}{5}, \hat{p}_{\circlearrowright}^{(MLE)} = \frac{2}{5} \right)^T$$

- $\left(\hat{\pi}_{\circlearrowleft}^{(1)} = \frac{4}{5}, \hat{q}_{\bullet}^{(1)} = \frac{1}{2}, \hat{q}_{\circlearrowright}^{(1)} = 0 \right)^T$
- $\left(\hat{\pi}_{\circlearrowleft}^{(2)} = \frac{3}{5}, \hat{q}_{\bullet}^{(2)} = \frac{1}{3}, \hat{q}_{\circlearrowright}^{(2)} = \frac{1}{2} \right)^T$
- $\left(\hat{\pi}_{\circlearrowleft}^{(3)} = \frac{3}{5}, \hat{q}_{\bullet}^{(3)} = 0, \hat{q}_{\circlearrowright}^{(3)} = \frac{2}{3} \right)^T$

$$\begin{pmatrix} \hat{p}_{\circlearrowleft} \\ \hat{p}_{\bullet} \\ \hat{p}_{\circlearrowright} \end{pmatrix} = \Phi \begin{pmatrix} \hat{\pi}_{\circlearrowleft} \\ \hat{q}_{\bullet} \\ \hat{q}_{\circlearrowright} \end{pmatrix} = \begin{pmatrix} \hat{\pi}_{\circlearrowleft} \cdot (1 - \hat{q}_{\bullet}) \\ (1 - \hat{\pi}_{\circlearrowleft}) \cdot (1 - \hat{q}_{\circlearrowright}) \end{pmatrix}$$

Basic idea for the i.i.d. case

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{Y}_i), \quad i = 1, \dots, n$$

Use random-set perspective and determine maximum-likelihood estimator $\hat{p}_{\mathcal{Y}}$

Likelihood for parameters $\mathbf{p} = (p_1, \dots, p_{|\Omega_{\mathcal{Y}}|-1})^T$
 $L(\mathbf{p}) \propto \prod_{\mathcal{Y} \in \Omega_{\mathcal{Y}}} p_{\mathcal{Y}}^{n_{\mathcal{Y}}}$ is *uniquely* maximized by

$$\hat{p}_{\mathcal{Y}} = \frac{n_{\mathcal{Y}}}{n}, \quad \mathcal{Y} \in \{1, \dots, |\Omega_{\mathcal{Y}}|-1\}$$

and thus $\hat{p}_{|\Omega_{\mathcal{Y}}|} = 1 - \sum_{m=1}^{|\Omega_{\mathcal{Y}}|-1} \hat{p}_m$.

Observation model \mathcal{Q}
error-freeness

coarsening mechanism
 $q_{\mathcal{Y}|y} = P(\mathcal{Y} = \mathcal{Y} | Y = y)$

LATENT

Y latent variable

Main goal:

Estimation of $\pi_{ij} = P(Y_i = j)$
 $\pi_{i1} = \pi_1, \dots, \pi_{iK} = \pi_K$

Use the **connection**
between \mathbf{p} and $\boldsymbol{\gamma}$

$$\Phi(\boldsymbol{\gamma}) = \mathbf{p}$$

and the **invariance of the likelihood**
under parameter transformations, i.e.:

$$\hat{\Gamma} = \{\boldsymbol{\gamma} \mid \Phi(\boldsymbol{\gamma}) = \hat{\mathbf{p}}\}$$

$$\boldsymbol{\gamma} = (q_{\mathcal{Y}|y}^T, \boldsymbol{\pi}_y^T)^T$$

$$\hat{\boldsymbol{\pi}}_y \in \left[\frac{n_{(y)}}{n}, \frac{\sum_{\mathcal{Y} \ni y} n_{\mathcal{Y}}}{n} \right]$$
$$\hat{q}_{\mathcal{Y}|y} \in \left[0, \frac{n_{\mathcal{Y}}}{n_{(y)} + n_{\mathcal{Y}}} \right]$$

Basic idea for the i.i.d. case

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{Y}_i), i = 1, \dots, n$$

Use random-set perspective and determine maximum-likelihood estimator $\hat{p}_{\mathcal{Y}}$

Likelihood for parameters $\mathbf{p} = (p_1, \dots, p_{|\Omega_{\mathcal{Y}}|-1})^T$
 $L(\mathbf{p}) \propto \prod_{\mathcal{Y} \in \Omega_{\mathcal{Y}}} p_{\mathcal{Y}}^{n_{\mathcal{Y}}}$ is uniquely maximized by

$$\hat{p}_{\mathcal{Y}} = \frac{n_{\mathcal{Y}}}{n}, \quad \mathcal{Y} \in \{1, \dots, |\Omega_{\mathcal{Y}}| - 1\}$$

and thus $\hat{p}_{|\Omega_{\mathcal{Y}}|} = 1 - \sum_{m=1}^{|\Omega_{\mathcal{Y}}|-1} \hat{p}_m$.

← Observation model \mathcal{Q}
error-freeness

coarsening mechanism
 $q_{\mathcal{Y}|y} = P(\mathcal{Y} = \mathcal{Y} | Y = y)$

Use the connection
between \mathbf{p} and $\boldsymbol{\gamma}$
← $\Phi(\boldsymbol{\gamma}) = \mathbf{p}$

and the invariance of the likelihood under parameter transformations, i.e.:

$$\hat{\Gamma} = \{\boldsymbol{\gamma} \mid \Phi(\boldsymbol{\gamma}) = \hat{\mathbf{p}}\}$$

LATENT

Y latent variable

Main goal:

Estimation of $\pi_{ij} = P(Y_i = j)$
 $\pi_{i1} = \pi_1, \dots, \pi_{iK} = \pi_K$

$$\boldsymbol{\gamma} = (q_{\mathcal{Y}|y}^T, \boldsymbol{\pi}_y^T)^T$$

$$\hat{\pi}_y \in \left[\frac{n_{(y)}}{n}, \frac{\sum_{\mathcal{Y} \supseteq y} n_{\mathcal{Y}}}{n} \right]$$
$$\hat{q}_{\mathcal{Y}|y} \in \left[0, \frac{n_{\mathcal{Y}}}{n_{(y)} + n_{\mathcal{Y}}} \right]$$

Basic idea for the i.i.d. case

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{Y}_i), \quad i = 1, \dots, n$$

Use random-set perspective and determine maximum-likelihood estimator $\hat{p}_{\mathcal{Y}}$

Likelihood for parameters $\mathbf{p} = (p_1, \dots, p_{|\Omega_{\mathcal{Y}}|-1})^T$
 $L(\mathbf{p}) \propto \prod_{\mathcal{Y} \in \Omega_{\mathcal{Y}}} p_{\mathcal{Y}}^{n_{\mathcal{Y}}}$ is *uniquely* maximized by

$$\hat{p}_{\mathcal{Y}} = \frac{n_{\mathcal{Y}}}{n}, \quad \mathcal{Y} \in \{1, \dots, |\Omega_{\mathcal{Y}}| - 1\}$$

and thus $\hat{p}_{|\Omega_{\mathcal{Y}}|} = 1 - \sum_{m=1}^{|\Omega_{\mathcal{Y}}|-1} \hat{p}_m$.

← Observation model \mathcal{Q}
error-freeness

coarsening mechanism
 $q_{\mathcal{Y}|y} = P(\mathcal{Y} = \mathcal{Y} | Y = y)$

Use the **connection**
between \mathbf{p} and $\boldsymbol{\gamma}$

$$\Phi(\boldsymbol{\gamma}) = \mathbf{p}$$

and the **invariance of the likelihood**
under parameter transformations, i.e.:

$$\hat{\Gamma} = \{\boldsymbol{\gamma} \mid \Phi(\boldsymbol{\gamma}) = \hat{\mathbf{p}}\}$$

LATENT

Y latent variable

Main goal:

Estimation of $\pi_{ij} = P(Y_i = j)$
 $\pi_{i1} = \pi_1, \dots, \pi_{iK} = \pi_K$

$$\boldsymbol{\gamma} = (q_{\mathcal{Y}|y}^T, \boldsymbol{\pi}_y^T)^T$$

$$\hat{\pi}_y \in \left[\frac{n_{(y)}}{n}, \frac{\sum_{\mathcal{Y} \geq y} n_{\mathcal{Y}}}{n} \right]$$
$$\hat{q}_{\mathcal{Y}|y} \in \left[0, \frac{n_{\mathcal{Y}}}{n_{(y)} + n_{\mathcal{Y}}} \right]$$

Illustration (PASS data)

$n_{<} = 238, n_{\geq} = 835, n_{na} = 338$

$$\hat{\pi}_{<} \in \left[\frac{238}{1411}, \frac{238+338}{1411} \right]$$

Basic idea for the regression case

OBSERVABLE

\mathcal{Y} coarse data

LATENT

Y latent variable

Observation model \mathcal{Q}

error-freeness

coarsening mechanism

Main goal:

Estimation of $\pi_{ij} = P(Y_i = j)$

$$p_{x\vartheta_i} = P(\mathcal{Y}_i = \vartheta_i | X = x), \quad i = 1, \dots, n$$

$$x \in \{0, 1\}$$

$$q_{\vartheta|xy} = P(\mathcal{Y} = \vartheta | X = x, Y = y)$$

$$\pi_{ij} = P(Y_i = j | \mathbf{x}_i) = \frac{\exp(\beta_{j0} + \mathbf{x}_i^T \boldsymbol{\beta}_j)}{1 + \sum_{s=1}^{K-1} \exp(\beta_{s0} + \mathbf{x}_i^T \boldsymbol{\beta}_s)}$$

$$\pi_{iK} = (1 + \sum_{s=1}^{K-1} \exp(\beta_{s0} + \mathbf{x}_i^T \boldsymbol{\beta}_s))^{-1}$$

(multinomial logit model)

$$\boldsymbol{\gamma} = (q_{\vartheta|xy}^T, \boldsymbol{\pi}_y^T)^T$$

Use random-set perspective and determine maximum-likelihood estimator $\hat{p}_{x\vartheta}$

For fixed x , $(n_{x1}, \dots, n_{x|\Omega_y|}) \sim M(n_x, (p_{x1}, \dots, p_{x|\Omega_y|}))$ with conditional probabilities $p_{x\vartheta} = P(\mathcal{Y} = \vartheta | X = x)$.

Likelihood for parameters $\mathbf{p} = (p_{x1}, \dots, p_{x|\Omega_y|-1})^T$
 $L(\mathbf{p}) \propto \prod_{\vartheta \in \Omega_y} p_{0\vartheta}^{n_{0\vartheta}} \prod_{\vartheta \in \Omega_y} p_{1\vartheta}^{n_{1\vartheta}}$ is uniquely maximized by

$$\hat{p}_{x\vartheta} = \frac{n_{x\vartheta}}{n_x}, \quad \text{for } x \in \{0, 1\}.$$

Use the **connection**
between \mathbf{p} and $\boldsymbol{\gamma}$

$$\Phi(\boldsymbol{\gamma}) = \mathbf{p}$$

and the **invariance of the likelihood** under parameter transformations, i.e.:

$$\hat{\Gamma} = \{\boldsymbol{\gamma} \mid \Phi(\boldsymbol{\gamma}) = \hat{\mathbf{p}}\}$$

$$\hat{\pi}_{xy} \in \left[\frac{n_{x(y)}}{n_x}, \frac{\sum_{\vartheta \in \Omega_y} n_{x\vartheta}}{n_x} \right]$$

$$\hat{q}_{\vartheta|xy} \in \left[0, \frac{n_{x\vartheta}}{n_{x(y)} + n_{x\vartheta}} \right]$$

Basic idea for the regression case

OBSERVABLE

\mathcal{Y} coarse data

$$p_{x\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{Y}_i | X = x), \quad i = 1, \dots, n$$

$$x \in \{0, 1\}$$

Use random-set perspective and determine maximum-likelihood estimator $\hat{p}_{x\mathcal{Y}}$

For fixed x , $(n_{x1}, \dots, n_{x|\Omega_{\mathcal{Y}}|}) \sim M(n_x, (p_{x1}, \dots, p_{x|\Omega_{\mathcal{Y}}|}))$ with conditional probabilities $p_{x\mathcal{Y}} = P(\mathcal{Y} = \mathcal{Y} | X = x)$.

Likelihood for parameters $\mathbf{p} = (p_{x1}, \dots, p_{x|\Omega_{\mathcal{Y}}|-1})^T$
 $L(\mathbf{p}) \propto \prod_{\mathcal{Y} \in \Omega_{\mathcal{Y}}} p_{0\mathcal{Y}}^{n_{0\mathcal{Y}}} \prod_{\mathcal{Y} \in \Omega_{\mathcal{Y}}} p_{1\mathcal{Y}}^{n_{1\mathcal{Y}}}$ is uniquely maximized by

$$\hat{p}_{x\mathcal{Y}} = \frac{n_{x\mathcal{Y}}}{n_x}, \quad \text{for } x \in \{0, 1\}.$$

← Observation model \mathcal{Q}
error-freeness

coarsening mechanism

$$q_{\mathcal{Y}|xy} = P(\mathcal{Y} = \mathcal{Y} | X = x, Y = y)$$

Use the connection between \mathbf{p} and $\boldsymbol{\gamma}$

← $\Phi(\boldsymbol{\gamma}) = \mathbf{p}$

and the invariance of the likelihood under parameter transformations, i.e.:

$$\hat{\Gamma} = \{\boldsymbol{\gamma} \mid \Phi(\boldsymbol{\gamma}) = \hat{\mathbf{p}}\}$$

LATENT

Y latent variable

Main goal:

Estimation of $\pi_{ij} = P(Y_i = j)$

$$\pi_{ij} = P(Y_i = j | \mathbf{x}_i) = \frac{\exp(\beta_{j0} + \mathbf{x}_i^T \boldsymbol{\beta}_j)}{1 + \sum_{s=1}^{K-1} \exp(\beta_{s0} + \mathbf{x}_i^T \boldsymbol{\beta}_s)}$$

$$\pi_{iK} = (1 + \sum_{s=1}^{K-1} \exp(\beta_{s0} + \mathbf{x}_i^T \boldsymbol{\beta}_s))^{-1}$$

(multinomial logit model)

$$\boldsymbol{\gamma} = (q_{\mathcal{Y}|xy}^T, \boldsymbol{\pi}_y^T)^T$$

$$\hat{\pi}_{xy} \in \left[\frac{n_{x(y)}}{n_x}, \frac{\sum_{\mathcal{Y} \ni y} n_{x\mathcal{Y}}}{n_x} \right]$$

$$\hat{q}_{\mathcal{Y}|xy} \in \left[0, \frac{n_{xy}}{n_{x(y)} + n_{xy}} \right]$$

Illustration (PASS data)

$$\hat{\pi}_{0<} \in [0.41, 0.64] \quad \hat{\pi}_{1<} \in [0.10, 0.34]$$

$$\hat{\beta}_{<0} \in [-0.37, 0.59] \quad \hat{\beta}_{<} \in [-1.83, -1.25]$$

Starting from point-identifying assumptions, we use sensitivity parameters to allow inclusion of partial knowledge.

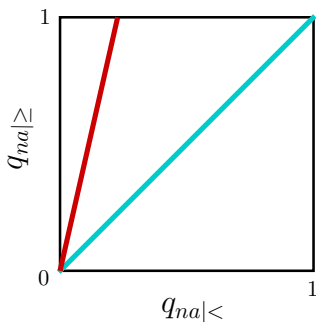
Assumption about exact value

of $R = \frac{q_{na|\geq}}{q_{na|<}}$ (Nordheim, 1984):

e.g. Q specified by $R=1$, $R=4$

where $R=1$ corresponds to CAR

(Heitjan, Rubin, 1991).



Starting from point-identifying assumptions, we use sensitivity parameters to allow inclusion of partial knowledge.

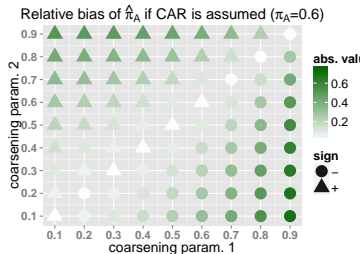
Assumption about exact value

of $R = \frac{q_{na|\geq}}{q_{na|<}}$ (Nordheim, 1984):

e.g. Q specified by $R=1$, $R=4$

where $R=1$ corresponds to CAR

(Heitjan, Rubin, 1991).



Starting from point-identifying assumptions, we use sensitivity parameters to allow inclusion of partial knowledge.

Assumption about exact value

of $R = \frac{q_{na|\geq}}{q_{na|<}}$ (Nordheim, 1984):

e.g. Q specified by $R=1$, $R=4$

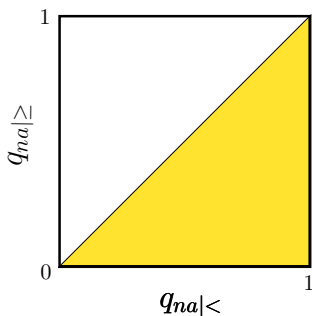
where $R=1$ corresponds to CAR

(Heitjan, Rubin, 1991).

Rough evaluation of R :

e.g. Q specified by $R \leq 1$:

low income group has a higher tendency to report "na"



- $R = \frac{q_{na|\geq}}{q_{na|<}}$: sensitivity parameter $\delta \in \Delta$
- Honestly Estimated Ignorance Region (HEIR)
 $\hat{ir}(\pi_Y, \Delta)$

- **Example 1:** No knowledge about R

$$\Rightarrow \hat{ir}(\pi_{<}, [0, \infty)) = \left[\frac{n_{<}}{n_{<} + n_{\geq} + n_{na}}, \frac{n_{<} + n_{na}}{n_{<} + n_{\geq} + n_{na}} \right]$$

- **Example 2:** $R \leq 1$

$$\Rightarrow \hat{ir}(\pi_{<}, [0, 1]) = \left[\frac{n_{<}}{n_{<} + n_{\geq} + n_{na}}, \frac{n_{<}}{n_{<} + n_{\geq}} \right]$$

How to adopt for uncertainty induced by finite sampling?

Uncertainty regions...

... for the ignorance region?

... for the parameter of interest?

Likelihood

$$\begin{aligned} & L(\pi_{<}, q_{na|<}, q_{na|\geq} || \mathbf{y}_1, \dots, \mathbf{y}_n) \\ & \propto ((1 - q_{na|<}) \cdot \pi_{<})^{n_{<}} \cdot ((1 - q_{na|\geq}) \cdot (1 - \pi_{<}))^{n_{\geq}} \\ & \quad \cdot (q_{na|<} \cdot \pi_A + q_{na|\geq} \cdot (1 - \pi_{<}))^{n_{na}} \end{aligned}$$

Likelihood ratio test:

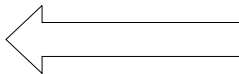
- $H_0 : \gamma = \gamma_0$ $H_1 : \gamma \neq \gamma_0$
- $LQ = 2 \log \frac{L(\hat{\gamma}_{ML})}{L(\hat{\gamma}_{0,ML})} = 2 \log(I(\hat{\gamma}_{ML}) - I(\hat{\gamma}_{0,ML}))$
- Reject H_0 if $LQ \geq \chi_{dim(\gamma)}^2$

Basic problem, now: Bayesian approach

OBSERVABLE

\mathcal{Y} coarse data

$$p_{\mathcal{Y}_i} = P(\mathcal{Y}_i = \mathcal{y}_i), \quad i = 1, \dots, n$$



coarsening mechanism

$$q_{\mathcal{Y}_i|\mathcal{y}_i} = P(\mathcal{Y}_i = \mathcal{y}_i | Y_i = y_i)$$

LATENT

Y latent variable

Main goal:

Estimation of

$$\pi_{ij} = P(Y_i = j)$$

1. Frequentist approach:

Find maximum-likelihood estimator of

$$\boldsymbol{\gamma} = (\mathbf{q}_{\mathcal{Y}_i|\mathcal{y}_i}^T, \boldsymbol{\pi}_y^T)^T$$

(i.i.d. case , regression case)

2. Bayesian approach:






Find posterior mean

(Next step)

- Via the observation model Q maximum-likelihood estimators referring to the latent variable may be obtained for both cases
 - ... the homogeneous case
 - ... the case with categorical covariates
- Proper inclusion of auxiliary information via further restrictions on Q

Next steps:

- Likelihood-based hypothesis tests and uncertainty regions for coarse categorical data
- Inclusion of auxiliary information via sets of priors
- Consideration of other “deficiency” processes

-  Couso, I., Dubois, D., Sánchez, L.
Random Sets and Random Fuzzy Sets as Ill-Perceived Random Variables, Springer, 2014.
-  Heitjan, D., Rubin, D.
Ignorability and Coarse Data, *Annals of Statistics*, 1991.
-  Manski, C.
Partial Identification of Probability Distributions, Springer, 2003.
-  E. Nordheim.
Inference from nonrandomly missing categorical data: An example from a genetic study on Turner's syndrome, *J. Am. Stat. Assoc.*, 1984.
-  Vansteelandt, S., Goetghebeur, E., Kenward, M., Molenberghs, G.
Ignorance and uncertainty regions as inferential tools in a sensitivity analysis, *Stat. Sin.*, 2006.